Chapter 5

Mapping the maze of Minimally Invasive Surgery simulators

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Abstract

Background: Conforming to, among other considerations, legal and ethical concerns for patient safety, there is an increasing demand to assess a surgeon's skills prior to performance in the operating room in pursuit of higher-quality treatment. Training in minimally invasive surgery (MIS) must therefore be intensified, including team training. New methods to train and assess minimally invasive surgical skills are gaining interest. The goal of this review is to provide instructors with an overview of available MIS training tools. In this review, we discuss currently available simulators for MIS training. Applicability, validity, and construction of simulators are reviewed. Also, some of the leading training programmes and assessment methods in MIS are reviewed.

Methods: A literature search was performed on studies evaluating surgical task performance on a simulator, reviewing satisfaction with laparoscopic training programmes, or validating simulators or assessment methods.

Results: Simulators may be divided into simple box trainers and computer-based systems, such as virtual- and augmented simulators. All have advantages and disadvantages. An overview is provided of currently available training systems, validity, trainee assessment, and the importance of training programmes in MIS.

Conclusions: No simulator yet provides the ability to train the entire set of required psychomotor skills or procedures for MIS. A multi-year training programme combining various simulators for multiple-level training, including team training, should be constructed.
Introduction

The introduction of minimally invasive surgery (MIS) has reduced the surgical burden for many patients because of the use of minimal incisions and videoscopic technology. MIS has changed the landscape of surgery during the past two decades; postoperative pain has been diminished, patients mobilize earlier after MIS and hospital stays are shorter, beside obvious cosmetic advantages. Because of these advantages, many open procedures are being replaced by MIS.

At the onset of MIS in the early 1990’s, comprehensive training in MIS was not available. Many of the early adapters of MIS were their own teachers, associated with long operating hours. Complications such as bile duct injury during laparoscopic cholecystectomy were more common in the early phase of MIS compared to open surgery because optimal MIS operative approaches and technologies had not yet been fully established\(^1\). The transition from a three-dimensional working field to a two-dimensional image projected on TV monitor with consequent loss of accurate palpation of vital structures and pathology was one of the largest transformations in surgical techniques this past century. Additionally, impaired tactile feedback, loss of joint dexterity and counterintuitive instrument movement render MIS a different technique compared to open surgery\(^2\).

To ensure patient safety, adequate training of MIS is mandatory\(^3\).

A spectrum of training scenario’s - inanimate training, training on live or cadaveric animal tissues, box trainers, virtual reality (VR) and augmented reality (AR) simulators, and training on cadaveric human tissues - is available\(^4\)\(^7\).

The aim of this study is to provide an overview of available simulators in MIS. We offer an aid to surgical educators in choosing a simulator for MIS-training. We
present recommendations for optimal use of specific MIS-simulators within different stages of a surgical curriculum.

**Methods**

Eligible studies were identified using an extensive and systematic search conducted in February 2011 using MEDLINE/Pubmed (Table 1). We included all articles focused on surgical task performance on a simulator, reviewing satisfaction with laparoscopic training programmes, or validating simulators or assessment methods. Title and abstract of English articles identified by the database were scanned to assess inclusion eligibility. When information necessary for the assessment of eligibility was lacking, the full text article was retrieved for review. Additionally, related articles and reference lists of selected articles were scanned.

Knowledge of key-features is essential in choosing a training or assessment device. Evidence suggests that simulators are valid instruments in the acquisition of MIS skills. Hamilton et al. established that laparoscopic skills developed outside the operating room are transferrable to actual performance of laparoscopic surgery.

Teaching, rehearsal and assessment in simulator-based training always occur simultaneously. Feedback should provide residents with an indication of present performance. Furthermore the collected data allows evaluation of resident progression. Simulators may provide objective data that allows assessment of technical skills. Performance of surgical tasks improves by standardized repetition. Improvement is
exponential at the start. Subsequently, it levels off over time until a steady state of performance is established\textsuperscript{14}. A learning curve is the graphic representation of the relationship between experience and outcome. Outcome may be described as mortality, morbidity or towards scientific criteria such as procedure duration or instrument path length\textsuperscript{15}.

Table 1 – Ovid MEDLINE search strategy (search date, 28 February 2011)

<table>
<thead>
<tr>
<th>Number</th>
<th>Search history</th>
<th>Results</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
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<td>596824</td>
</tr>
<tr>
<td>3</td>
<td>1 and 2</td>
<td>2500</td>
</tr>
<tr>
<td>4</td>
<td>videotrain* OR box OR boxes OR boxtrain* OR simulat* OR virtual OR augmented</td>
<td>557333</td>
</tr>
<tr>
<td>5</td>
<td>2 and 4</td>
<td>1530</td>
</tr>
<tr>
<td>6</td>
<td>3 and 4, limits: English</td>
<td>615</td>
</tr>
<tr>
<td>7</td>
<td>5 not 6, limits: English</td>
<td>838</td>
</tr>
<tr>
<td>8</td>
<td>&quot;Laparoscopy&quot;[Mesh]</td>
<td>44883</td>
</tr>
<tr>
<td>9</td>
<td>8 and 6</td>
<td>601</td>
</tr>
<tr>
<td>10</td>
<td>8 and 7</td>
<td>767</td>
</tr>
</tbody>
</table>
**Reliability**

Reliability is the reproducibility and consistency of results or examination in a simulator. Test-retest reliability is the commonly used indicator for instrumental reliability; it is estimated by performing the same survey with the same respondents on a comparable level at different moments in time. The greater the agreement of results, the greater the test-retest reliability of the survey instrument\(^\text{16}\).

**Validity**

Validity is “the property of being true, correct, and in conformity with reality.” Validity indicates whether a simulator measures the skill it is intended to measure. According to the European Association of Endoscopic Surgeons (EAES) consensus guidelines drawn from Carter et al.\(^\text{17}\), there is a need for a validation of the MIS simulators and their assessment methods, before their inclusion into training curricula. A simulator must be evaluated vigorously and objectively regarding its reliability and validity\(^\text{16,18}\).

Validation contains several principles, and to assess the validity of a training device or assessment method several benchmarks have been developed. These include construct, face, predictive, content, concurrent and discriminate –validity\(^\text{17,19}\). Construct validity is defined as correctly simulating or measuring the skills it intends to train or assess\(^\text{20}\).

Face validity illustrates adequate simulation and adequate resemblance to a task and whether a simulator is considered useful for training\(^\text{21-23}\). Predictive validity is the extent to which a score predicts scores on defined criterion measures in the future. This is the extent to which scores on a test are predictive of actual performance in operating room.
Content validity is an indication of the appropriateness of a simulator as a teaching tool.

Correlation of test scores between two devices or a device and the gold standard - which are assumed to measure the same variable - is defined as concurrent validity. Discriminate validity describes the translation of simulator skill to skill in the operating room.

Validation may take a subjective and objective approach. Face and content validity both are subjective approaches to validity. Content validity requires two groups of different skill levels to perform a procedure or assessment, after which both groups are asked their opinion whether the tested device and procedures resembles the real life experience. Face validity involves a questionnaire exploring two groups of different skill level’s opinion on the training or assessment method. Objective approaches to validity include construct, discriminative, concurrent, and predictive validity. These validities generally involve studies investigating whether a simulator provides metrics for performance or discriminates among different levels of expertise. When investigating training programs a key question to objective approaches of validity is whether training on inanimate systems is transferable to operating room conduct. Simulator metrics display predictive validity when they show correlation with objective assessment of in vivo skill. Predictive validity actually provides here the only meaningful assessment of clinical skills, while the other validity measures focus on the training methods and outcomes.

**Training Systems**
Several studies have examined the training capacities of various surgical simulators\textsuperscript{23,24}. Training on simulators increases psychomotor skills, which translates into improved performance in MIS before performing on animate models and patients\textsuperscript{25}. MIS simulators are computerized VR simulators, traditional video box trainers or a combination of these\textsuperscript{26}. The use of MIS simulators results in faster acquisition of endoscopic technical skills compared with ample observation of an expert or practicing parts of procedures under supervision in the operating room\textsuperscript{27}. However, each simulator has its own advantages and disadvantages (Table 2). Several simulators have been developed and examined. Validated simulators available up to February 2011 are listed in table 3. We describe published data on efficacy, reliability and validity of available MIS training devices.
<table>
<thead>
<tr>
<th></th>
<th>Advantage</th>
<th>Disadvantage</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Box trainer</strong></td>
<td>- Inexpensive</td>
<td>- Lack of (data on) automatic and objective skill assessment tools</td>
</tr>
<tr>
<td></td>
<td>- Genuine haptic feedback</td>
<td>- Faculty required for training and exams</td>
</tr>
<tr>
<td></td>
<td>- Actual laparoscopic instruments</td>
<td></td>
</tr>
<tr>
<td></td>
<td>- Practice on genuine cadaveric tissue</td>
<td></td>
</tr>
<tr>
<td><strong>Virtual Reality simulator</strong></td>
<td>- Simulation of specific surgical procedures</td>
<td>- Relatively expensive</td>
</tr>
<tr>
<td></td>
<td>- Automatic and objective skill assessment</td>
<td>- No realistic haptic feedback</td>
</tr>
<tr>
<td></td>
<td>- No faculty required</td>
<td>- No realistic anatomy</td>
</tr>
<tr>
<td></td>
<td></td>
<td>- Frequent maintenance/update</td>
</tr>
<tr>
<td></td>
<td></td>
<td>- Possibility of routine practice</td>
</tr>
<tr>
<td><strong>Augmented Reality simulator</strong></td>
<td>- Genuine haptic feedback</td>
<td>- Relatively expensive</td>
</tr>
<tr>
<td></td>
<td>- Actual laparoscopic instruments</td>
<td>- Vision-tracking systems sensitive to malfunction</td>
</tr>
<tr>
<td></td>
<td>- Practice on genuine cadaveric tissue</td>
<td>- Possibility of routine practice</td>
</tr>
<tr>
<td></td>
<td></td>
<td>- Lack of assessment</td>
</tr>
</tbody>
</table>
- Simulation of specific surgical procedures
- Automatic and objective skill assessment
- No need of faculty protocols

Box trainers

Real life surgical conditions are probably best obtained by box trainers (video trainers) as box trainers use conventional laparoscopic equipment inserted through trocars, include video monitor and camera and provide the possibility of the introduction of a range of targets for practice such as synthetic inanimate models or real cadaver tissue. It thereby provides an ideal environment for training different surgical scenarios. The box typically measures the same size as an adult human.
abdominal cavity. Main exercises in a box trainer include movement, coordination and procedural training. The use of real tissue has many advantages, such as haptic feedback and an acquaintance with different types of tissue. Haptic feedback is described as the experience of force feedback when manipulating tissue. Training in the absence of haptic feedback significantly decreases the amount of skill transferred to the operating room when compared with training in the presence of haptic feedback. As such, we feel it is essential to provide haptic feedback when training MIS skills. Furthermore, several key aspects of learning skills involve a trainee’s subtle interaction with tissue and suturing materials (haptic feedback). Visual feedback alone does not suffice.

Several box and video trainers including various validated exercises are available. An overview is given in table 4. The use of a laparoscopic box trainer is particularly well documented in the McGill Inanimate System for Training and Evaluation of Laparoscopic Skills (MISTELS). The MISTELS system was designed to objectively assess basic laparoscopic skills through a series of structured tasks performed under video guidance in a box trainer. MISTELS has been shown to discriminate between competent and non-competent laparoscopic surgeons and may be used to evaluate individual skill levels. These box trainers have been studied and validated extensively and have progressed into the Fundamentals of Laparoscopic Surgery training course and evaluation system (FLS).

Box trainers do not instantly provide feedback on performance. Therefore, educators (most often experienced surgeons) must evaluate skill parameters when using a box trainer. Mostly the objective structured assessment of technical skills (OSATS) is used for the objectively assessing skills on a traditional box trainer. OSATS was first described by Martin et al. and Reznick et al. and is based on a structured clinical
examination format, using a combination of checklists and global rating scores to judge performance. Consequently, metrics for box trainers are subject to inter- and intra-observer variation, and an -often- expensive faculty member must always be present for examination purposes. However, compared to most other training systems, the box trainer is still relatively inexpensive.\textsuperscript{3,36}

**Table 4 – Box- & Videotainers**

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Validity*</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yale laparoscopic skills and suturing program\textsuperscript{41}</td>
<td>Laparoscopic surgical trainer</td>
<td>3</td>
</tr>
<tr>
<td>Lentz (6 tasks)\textsuperscript{67}</td>
<td>Mirrored box trainer</td>
<td>3</td>
</tr>
<tr>
<td>Risucci\textsuperscript{88}</td>
<td>Box trainer</td>
<td>3</td>
</tr>
<tr>
<td>McGill inanimate system for training and evaluations of laparoscopic skills (MISTELS)\textsuperscript{89}</td>
<td>Box trainer</td>
<td>1,3 &amp; 4</td>
</tr>
<tr>
<td>Southwestern video trainer stations\textsuperscript{90}</td>
<td>Video trainer</td>
<td>1,3 &amp; 4</td>
</tr>
<tr>
<td>Black (5 tasks)\textsuperscript{91}</td>
<td>Video trainer</td>
<td>3</td>
</tr>
<tr>
<td>Fundamentals of laparoscopic surgery (FLS)\textsuperscript{92}</td>
<td>Box trainer</td>
<td>1,3 &amp; 4</td>
</tr>
<tr>
<td>SIMULAB\textsuperscript{93}</td>
<td>Lap trainer with</td>
<td>1 &amp; 3</td>
</tr>
<tr>
<td>Legacy inanimate system for laparoscopic team training (LISETT)\textsuperscript{94}</td>
<td>Ethicon Laptrainer</td>
<td>3</td>
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<tr>
<td>Pelv-Sim\textsuperscript{95}</td>
<td>Pelv-Sim box trainer</td>
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<tr>
<td>Kolkman (5 tasks)\textsuperscript{96}</td>
<td>Box trainer</td>
<td>3</td>
</tr>
<tr>
<td>Clevin (5 tasks)\textsuperscript{97}</td>
<td>Box trainer</td>
<td>3</td>
</tr>
</tbody>
</table>

* 1. face, 2. content, 3. construct, 4. predictive, 5. concurrent, 6. discriminative

**Example of box trainer implementation: FLS program**

A laparoscopic training device should be integrated into laparoscopic training programmes, and a training curriculum should be designed before choosing a training system. The FLS program, designed in 2004 by a committee of the Society of American Gastrointestinal Endoscopic Surgery and based on the laparoscopic box trainer, is an excellent example of a curriculum covering the basics in laparoscopic surgery. The FLS contains comprehensive coverage of cognitive (declarative knowledge) and psychomotor (procedural skill) components. The FLS includes educational material, mechanisms for assessment, and a didactic instruction.\textsuperscript{52}

Within the FLS, five training modules are combined, including peg transfer, pattern cutting, ligating loop, and intracorporeal and extracorporeal knot tying.\textsuperscript{48,49}

The FLS exam is a combination of a written exam and a timed and scored laparoscopic skills evaluation in the box trainer. All tasks are scored according to pre-
established standards using time and error measurements. Exams in the FLS are conducted by trained examiners using standardized criteria, enabling trainees to undergo a certification process. The MISTELS is used within the FLS to assess technical skill. The FLS exams are only available to a few centres in the USA and Canada. Consequently participation in the FLS system is expensive for participants following an individual residency program outside these two countries.

In numerous studies, the FLS program has been found to be a valid teaching and assessment tool for laparoscopic knowledge and skills. Performance in the FLS has also been shown to correlate with operative performance.

**Virtual Reality Simulators**

Recent advances in VR technology have led to the development of VR simulators for acquiring surgical skills and a measurement of performance or skill. VR simulators are computer-based. VR technology has developed software that attempts to replicate skills required for entire MIS procedures, such as cutting, grasping and suturing and thereby enabling the operator to acquire the psychomotor skills necessary to perform these procedures. VR software generates three-dimensional images on a two-dimensional monitor, which may appear unrealistic. It is important for a trainee to practice an entire procedure including decision making options and not only basic suturing and knot-tying tasks, including theory lessons. Haptic feedback provided on VR simulators is often absent or relatively poor compared with haptic feedback provided in box trainers.

VR simulators provide an instant, unbiased, reliable and valid assessment of technical MIS skills. Most of the currently validated VR simulators use time,
errors and psychomotor related parameters for assessment such as path length travelled by instruments. The assessment and feedback provided by a VR simulator aim to only improve the psychomotor skills of a trainee. As a result, VR simulators do not require the presence of an educator to assess the trainee. Several VR simulators have been developed and examined. Validated simulators available up to February 2011 are listed in table 4. Below we discuss some of most commonly used VR simulators.

One of the first and most commonly used VR simulators developed as a task trainer is the Minimally Invasive Surgical Trainer-Virtual Reality (MIST-VR) (Mentice AB, Göteborg, Sweden). The device contains three modules: MIST Core Skills 1 & 2 contain simple tasks designed to acquire psychomotor skills and the MIST suturing module is designed to train needle handling, suturing, and knot tying. The original MIST system does not provide haptic feedback or a VR abdominal environment. The Procedicus system, an optional modular simulation environment built by SimSurgery A/S (Oslo, Norway), additionally provides haptic feedback and different modules in an abdominal environment to the MIST-VR. The MIST-VR is the most extensively studied and validated system regarding construct, face and concurrent validity and the assessment of basic laparoscopic skills in MIS. The MIST-VR does not assess cognitive knowledge or complete laparoscopic procedures including intraoperative problem solving. The system provides real-time feedback regarding skill-based errors based on an electromagnetic field. A web-enabled platform allows for remote performance monitoring and administration.

The LapSim VR laparoscopic simulator (Surgical Science, Göteborg) has a high degree of realism regarding graphics and tissue-instrument interaction. The system provides nine realistic tasks that closely resemble an operative field. Objects are
deformable and may ‘bleed.’ The LapSim also features a scoring game module that integrates different skills at various levels coupled to a scoring system. Haptic feedback is optional. Various studies have proven construct, face, and content validity of the LapSim and its ability to distinguish between novice and experienced laparoscopic surgeons.66-68

The SIMENDO (DeltaTech, Delft, The Netherlands) is a laparoscopic simulator designed to train hand-eye coordination motor skills. It provides an easy-to-use plug-and-play system for surgical trainees. The system does not provide haptic feedback. Verdaasdonk et al.69 established content, face, and concurrent validity of the SIMENDO and found construct validity for the simulator training program. To produce objective assessments, the SIMENDO includes the parameters task time, instrument collisions with non-target objects, and total path length for the right and left instruments.70 The SIMENDO is able to participate in a serious online gaming environment, creating an online competition for VR simulation training. This stimulates voluntary skills training.71

The LapMentor VR laparoscopy simulator (Simbionix, Cleveland, OH, USA) is an adapted version of the LS500 surgical simulator with added haptic feedback. The device may be used to practice basic laparoscopic skills as well as complex skills and total surgical laparoscopic procedures, (e.g. a laparoscopic cholecystectomy). Face validation of the Simbionix LapMentor VR training module was demonstrated by Ayodeji et al.59 A virtual instructor guides the trainee and provides feedback during the simulation. Parameters used in assessments include total time, motion analysis parameters, and safety parameters (e.g., complications such as perforation and
blood loss). Didactic parameters are included as decision-making options such as conversion.

VR simulators provide rapid and precise results on many measures of skill and appear to be good instrument for the objective assessment of surgical skills.\textsuperscript{54;61;72;73} Various parameters are utilized for feedback and assessment purposes. Most VR systems provide objective feedback on time, path length, and motion efficiency. However, most commercially available VR simulators are offered with a broad range of options and no predefined criteria or information regarding the intensity or duration of training needed to achieve surgical competence. Beside the expensive hardware, VR simulator software is often expensive and requires frequent maintenance and updating.\textsuperscript{7}

**AR simulators**

AR combines physical reality (such as in a box trainer) and VR into one system. Haptic feedback is maintained, using original laparoscopic instruments and tactile tasks. Additionally, objective measures of performance are generated.\textsuperscript{66} AR devices are equipped with modules that simulate a laparoscopic environment and allow performance of tasks related to the box trainer tasks within the construct of the simulator.

Seven AR simulators are currently available. These simulators vary from relatively simple augmented box trainers with a separate assessment module to more advanced simulators including demo videos, projection of a realistic environment during performance, and assessment of performance.\textsuperscript{74} Hardware and software costs of an AR simulator are comparable to those of a VR simulator but depend on the modules purchased.
A widely used AR simulator is the ProMis AR laparoscopic simulator (Haptica Inc., Boston, MA, USA). The ProMis measures movements of marked instruments by a passive vision-tracking system. Three separate cameras capture the internal movements of marked laparoscopic instruments from three different angles. The tracking system is situated in a large mannequin, and its design allows measurement of motions in the x, y, and z directions. The distal end of a laparoscopic instrument shaft is covered with yellow electrical tape to serve as a reference point for the tracking systems.34 Construct and face validation for the ProMis was found by Van Sickle et al.34 Another widely used AR simulator is the SurgicalSIM (LTS3E) (METI, Sarasota, FL, USA), a video-laparoscopic training system based on an integrated Microsoft Windows (Redmond, WA, USA) computer and software. The simulator incorporates a sensor carousel to computerize scoring of performance. The system provides a set of ten skill and coordination tasks that are scored on speed and precision. Construct and concurrent validation of the SurgicalSIM was shown by Soyinka et al.75 and Mathis et al.76 Task performance scoring is based on MISTELS. A unique feature of this device is the optional addition of a ‘tensiometer’, which electronically verifies knot integrity. Knot integrity is defined as a tensile strength of at least 25 Newton. The SurgicalSIM has multiple training programs for general surgery, gynaecology and urology. A drawback includes the dependency of the SurgicalSIM on an electromagnetic field required for motion tracking. Consequently any metallic object used may disturb the electromagnetic field and therefore potentially invalidate any recorded tracking data. Only surgical instruments supplied with the simulator may be used.
A device that allows free manipulation of a standard MIS instrument and tracks its movements in any box trainer without using a surrounded infrared system is the TrEndo developed by Chmarra, et al.\textsuperscript{77} at the Delft University of Technology. The TrEndo system is a relatively new tracking device constructed as a trocar through which any MIS instrument may be inserted. The TrEndo consists of a two-axis gimbal mechanism with three optical eyes. The TrEndo aims to provide detailed performance assessment on inanimate box trainers. Tracked and recorded motions include path length, insertion distance, angular area, volume, and time as an objective quantitative measure of performance (motion analysis parameters). The TrEndo is a low-cost device that may be interesting for institutes already using box trainers.

**Discussion**

This review provides an overview of currently available MIS simulators and their established validity, reliability, and other central attributes. Simulator training provides an opportunity for repetitive practice and trial and error in the acquisition of new laparoscopic skills without pressure or consequence from clinical reality. Simulators are a solution to current working hour restrictions and scarce operating room resources and may bypass an early learning curve, the latter of which is associated with an increased complication rate and thus injury and discomfort to patients.\textsuperscript{78-80} All systems show a faster acquisition of basic psychomotor skills. However, no system is superior to any other.\textsuperscript{7} Low cost box trainers utilize authentic laparoscopic instruments, provide haptic feedback, and provide an opportunity to train numerous
individuals simultaneously.\textsuperscript{81} Validated box-trainer tasks can be used to measure performance based on a single assessment.\textsuperscript{51} A disadvantage of box trainers is obligatory use of the OSATS assessment method, rendering it subject to subjective supervisors’ interpretation and scoring. Motion tracking (e.g., by use of the TrEndo) may address this problem, as an automatic objective feedback and assessment instrument for box trainers. Motion-analyzing parameters may be combined with real-time assessment of knot quality using a tensiometer.\textsuperscript{82} Recruitment of supervisors and faculty time present the major expenses in using box trainers. Available VR and AR systems demand less faculty attendance during practice; however, limitations include a longer ‘warming up’ for the trainee to fully comprehend the system and a lack of standard validated assessment methods.\textsuperscript{65} Most VR & AR simulators have no validated predictive validity. Performance scores based on construct validity can not be used for proficiency-based training because an expert-derived performance score may be inaccurate.

It is imperative that key measurements such as time and path length are integrally evaluated because a non-integrative evaluation per variable is not sufficient to improve on overall MIS skills. Trainees must to be trained to attain a certain level of proficiency and not merely be assessed on the amount of training-time completed. None of the current simulators and assessment methods can provide all data required to make an all-inclusive evaluation physician’s MIS skills possible. All feedback provided by current available simulators is (still) less when not combined with an expert’s feedback.\textsuperscript{83}

We believe that VR will play an increasing role in the future, taking into account current VR software development (e.g., the integration of haptic feedback, anatomy
derived from computed tomography or magnetic resonance imaging datasets, and
serious gaming).
For a skills lab to invest in simulators, a validated, multi-year training programme on
multiple-level training should be developed. Specialists, residents, educationalists,
and industrial designers should collaborate in such development. We should learn
from similar difficulties regarding the use of simulators in training encountered in
other domains such as the military and aviation.\textsuperscript{84} It is imperative that training be
structured within a standardized curriculum.\textsuperscript{85} Such a curriculum should include more
than one training modality, ranging from a low-fidelity training suited for novices to
high-fidelity simulators that may simulate entire procedures. As observed by experts
in aviation, novices are more likely to effectively acquire skills when situated in a
simple simulation training environment than when directly placed in a ‘real life’
cockpit where the complexity of instrumentation combined with the pressure to
perform may be overwhelming.\textsuperscript{84} This makes the box trainer a good candidate for
inclusion in a curriculum for MIS training. Once basic laparoscopic skills have been
attained, and laparoscopic residents tend to become equally dextrous and confident
with both hands, the training programme may be extended with more complex virtual-
reality simulations and include entire procedures (e.g., cholecystectomy). It is
important to also regard anatomic variations, for seldom in real life with a
‘stereotypical’ situation be encountered. If such variations are not programmed into a
simulator, there will be a risk of awkward creativity, in which the trainee will design
his or her own techniques to face such challenges. Performance will then be
conforming to the optimal learning curve of the simulator itself, thereby defeating the
goals of the simulator and also patient treatment and safety.
If valid metrics are not used, reliable assessment is not possible. So far, reliability and validity studies have focused mainly on technical skills. Skill acquisition, of course essential, is not the only competency when performing surgery on patients. Surgeons also require a core knowledge base, clinical decision making and communicative skills, and the ability to think and work under stress in a team setting. All these aspects must be trained to perform a given task correctly. Therefore, it may be better to design and evaluate a comprehensive training program instead - as in most existing training - of only validating one aspect or part of a procedure that can be performed on a simulator. As Satava recently suggested, “Simulators are only of value within the context of a total educational curriculum, the technology must support the training goals.”

Given the ubiquity of threat and error effective teamwork is required to ensure safety. For choosing the right simulator for each concerned skill, more rigorous studies with longer follow-up of trainees and assessment of the influence of more peripheral aspects such as team training are needed.

Further research is needed to combine team training (crew resource management [CRM]) with single simulator training. As is known in aviation, CRM is required for a team, including recording and evaluation of errors. Participants can be effectively taught using briefing and debriefing approaches. CRM is defined as the mental processes used for gaining and maintaining situational awareness, for solving problems, and for making decisions such as conversion to open surgery if needed. The potential value of possible future simulators combining CRM, complete procedural performance, and automated direct feedback is immense. A laparoscopic box trainer is easy to deploy in an operating room for team training sessions. Only
three VR and AR simulators include some form of CRM (table 3). So far, there are no validation studies to evaluate these simulators' utility for CRM.

A limitation of present review includes a lack of available structured data. Because of a lack of standardization in published studies, outcomes were not easy comparable. No study had defined cut off points to differentiate competent and non-competent surgeons. Meta-analysis was therefore not possible. We choose to provide an overview of the most commonly used and completely validated simulators.

Unfortunately, most included validation studies did not estimate concurrent validity. Concurrent validity is difficult to measure as operation room conditions often differ from those in the laboratory and therefore are impossible to standardize. As most validation studies focused on the use of a simulator as a training device, more research is needed to confine validity concepts to the use of a simulator as an objective assessment method.

In conclusion, no existing simulator may teach the whole range of skills required for competent psychomotor skills or procedures in MIS. None of the methods of simulation examined in this study has shown better results than other forms of surgical training. Single simulators will not replace the commitment of surgical educators, but because of restricted working hours and ethical discussions, surgical residents will be forced to spend an increasing amount of time with MIS simulators. This is amplified by an increasing number of laparoscopic procedures compared with open surgery, in which the resident could study the required anatomy prior to performance of the similar procedure laparoscopically.

There is therefore a need for integrated standardized training programs specifically
designed to improve MIS competence during residence training, complemented by a mentored program including cognitive and communication competence tailored to individual needs.\textsuperscript{91-93} This program should constitute knowledge-based learning, a stepwise technical skills pathway, provision of ongoing feedback as based on validated metrics, and measurable progression toward proficiency goals, thereby enabling transfer to a realistic environment. Scott and Dunnington\textsuperscript{93} described the National Skills Curriculum designed by the American College of Surgeons; the College stated that ‘distributed, deliberate and structured practice using performance-based endpoints is an ideal method for teaching many technical skills using simulators to ensure “operating room readiness” for residents’.

In our opinion a comprehensive training program ideally combines the following multiple stages:

1. Training in MIS should be introduced in a surgical curriculum as early as possible.\textsuperscript{94} First, attention should be paid to the acquisition of basic laparoscopic skills, such as suturing to improve hand-eye coordination. This could be achieved by a basic course such as the FLS on a low cost box trainer or AR-system. Feedback on time, smoothness, and path length in a box trainer could be provided by using a tracking system. Examination at the end of the first year can be executed by experts using the OSATS scoring system.

2. Second, the trainee should participate in a theoretical course regarding steps in MIS procedures (e.g., the critical view of safety during a laparoscopic cholecystectomy).\textsuperscript{95} Practice should here include performance of entire procedures on a box trainer, VR-system, or an AR-system. Key steps are preferably trained in this way. Goals must be set and achieved prior to progression to the next stage.
3. Third, a team training programme should be developed and implemented to improve cognitive and interpersonal skills needed to manage a procedure within an organised operating room team. Team training has become an essential driving force in reducing medical errors and increasing communication in the operating room. Some of the new generation VR and AR simulators made the first steps toward team training (table 4), replacing the need for animal models and cadavers.96

In our opinion, above proposal for a curriculum will provide the trainee with a comprehensive training programme that provides full attention to not only technical skill but also critical steps procedural decision making and interpersonal management, which integrally will allow performing entire MIS procedures on patients in the operating room. A completely validated curriculum embedding technical skills training, assessments, and team training will still be subject to an ever-changing environment. Taking into consideration that an AR-system provides realistic haptic feedback but is considerably more expensive than other devices and that CRM, including serious gaming, is still in its infancy, we suggest a laparoscopic box trainer including a low cost motion tracking device would at this moment fit all stages. Continuous development and adaptation to new training devices and simulators will still be required.

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